Comparison of techniques for coupled earthquake and tsunami modeling

Lauren S. Abrahams^{1,1,1}, Eric M. Dunham^{1,1,1}, Lukas Krenz^{2,2,2}, Tatsuhiko Saito^{3,3,3}, and Alice-Agnes Gabriel^{4,4,4}

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Abstract

From interpreting data to scenario modeling of subduction events, numerical modeling has been crucial for studying tsunami generation by earthquakes. Seafloor instruments in the source region feature complex signals containing a superposition of seismic, ocean acoustic, and tsunami waves. Rigorous modeling is required to interpret these data and use them for tsunami early warning. However, previous studies utilize separate earthquake and tsunami models, with one-way coupling between them and approximations that might limit the applicability of the modeling technique. In this study, we compare four earthquaketsunami modeling techniques, highlighting assumptions that affect the results, and discuss which techniques are appropriate for various applications. Most techniques couple a 3D Earth model with a 2D depth-averaged shallow water tsunami model. Assuming the ocean is incompressible and that tsunami propagation is negligible over the earthquake duration leads to technique (1), which equates earthquake seafloor uplift to initial tsunami sea surface height. For longer duration earthquakes, it is appropriate to follow technique (2), which uses time-dependent earthquake seafloor velocity as a time-dependent forcing in the tsunami mass balance. Neither technique captures ocean acoustic waves, motivating newer techniques that capture the seismic and ocean acoustic response as well as tsunamis. Saito et al. (2019) propose technique (3), which solves the 3D elastic and acoustic equations to model the earthquake rupture, seismic wavefield, and response of a compressible ocean without gravity. Then, sea surface height is used as a forcing term in a tsunami simulation. A superposition of the earthquake and tsunami solutions provides the complete wavefield, with one-way coupling. The complete wavefield is also captured in technique (4), which utilizes a fully-coupled solid Earth and ocean model with gravity (Lotto & Dunham, 2015). This technique, recently incorporated into the 3D code SeisSol, simultaneously solves earthquake rupture, seismic waves, and ocean response (including gravity). Furthermore, we show how technique (3) follows from (4) subject to well-justified approximations.

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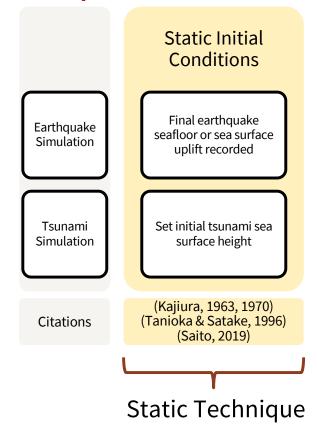
One-Way Coupled Techniques

Pass information from an earthquake simulation

one-way information flow

To separate tsunami simulation





Pass information from an earthquake simulation

one-way information

flow

To separate tsunami simulation



Static Initial Conditions

Earthquake Simulation

Tsunami Simulation

Citations

Final earthquake

seafloor or sea surface uplift recorded

Set initial tsunami sea surface height

(Kajiura, 1963, 1970) (Tanioka & Satake, 1996) (Saito, 2019) Time-dependent Seafloor Velocity as Forcing

Record earthquake seafloor velocity

Set time-dependent forcing in the tsunami mass balance

(Saito & Furumura, 2009) (Saito & Tsushima, 2016) (Saito, 2019)

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Time-dependent forcing

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one-way information flow

To separate tsunami simulation

Do not account for compressibility effects



Conditions

Earthquake

Simulation

Tsunami

Simulation

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Approximate approaches



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(Saito et al., 2019) (Saito, 2019) Fully Coupled Method (SeisSol)

Simultaneously solves earthquake rupture, seismic waves, and ocean response (including gravity)

http://www.seissol.org/

(Lotto & Dunham, 2015)

Approximate approaches

Considered "ground Tuck" Newly implemented in 3D

Static Initial Conditions

Earthquake
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Tsunami Sea Set initial tsunami sea surface height

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Model the full-wave field

One-Way Coupled Techniques

Pass information from an earthquake simulation

one-way information flow

To separate tsunami simulation

Model techniques:

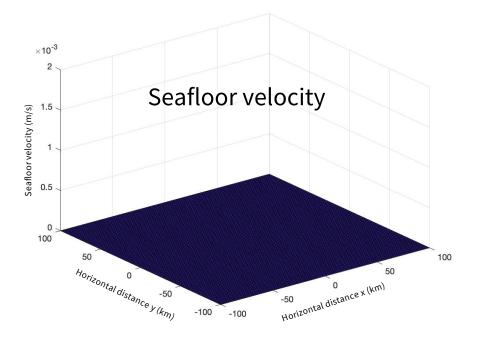
- Static initial conditions vs time-dependent forcing
- Incompressible vs compressible ocean

How is modeled data affected by:

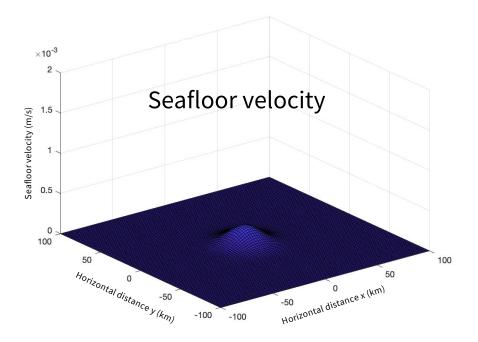
- 1. long rupture duration
- 2. acoustic wave generation



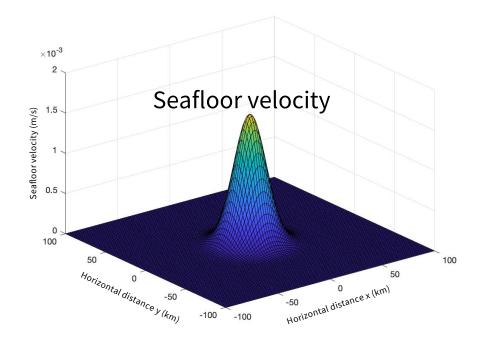




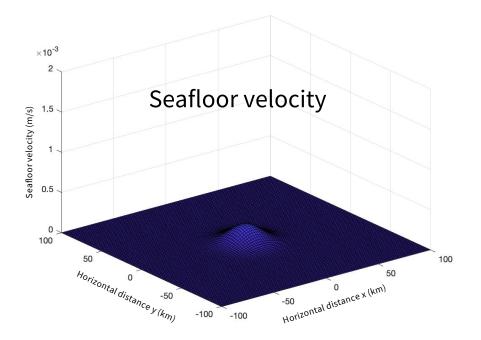




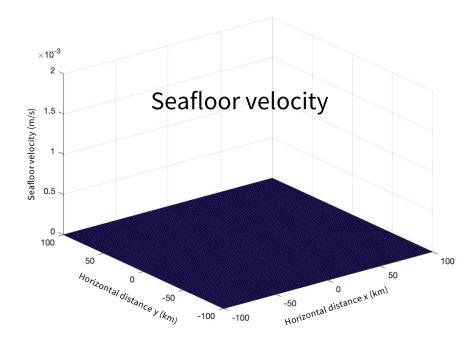






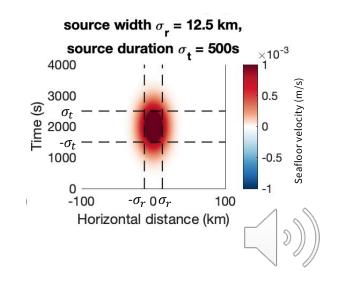




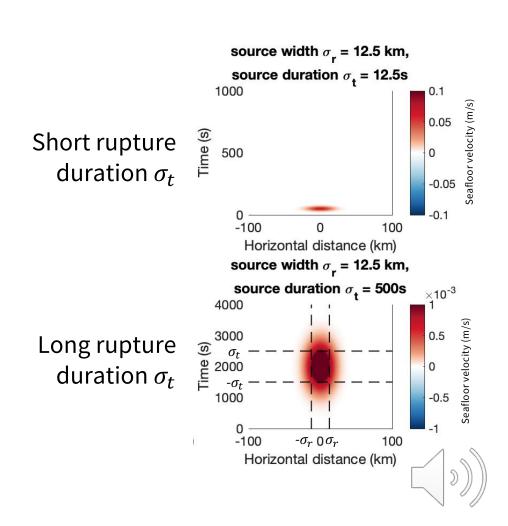




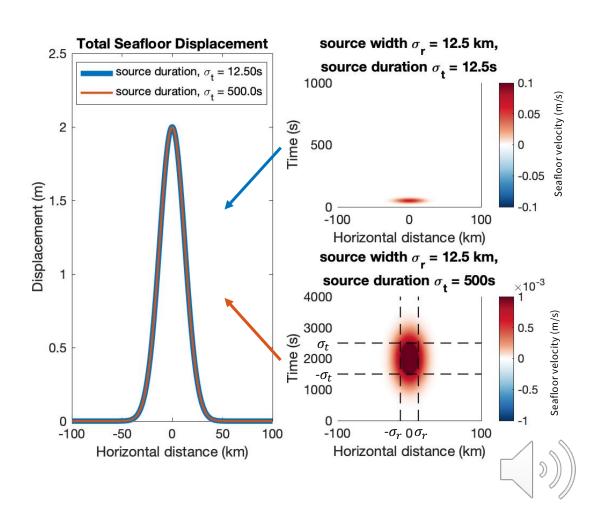
- We want to examine how long duration rupture and compressibility affect wave generation in the four modeling techniques
- We vary source width (σ_r) and duration (σ_t) in the earthquake simulation to test different scenarios setups



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- We want to examine how long duration rupture and compressibility affect wave generation in the four modeling techniques
- We vary source width (σ_r) and duration (σ_t) in the earthquake simulation to test different scenarios setups

Within shallow water limit? No if:

$$\frac{H}{\sigma_r} \gg 1$$

Tsunami propagates over source duration? No if:

$$\frac{\sigma_r}{\sigma_t \sqrt{gH}} \gg 1$$

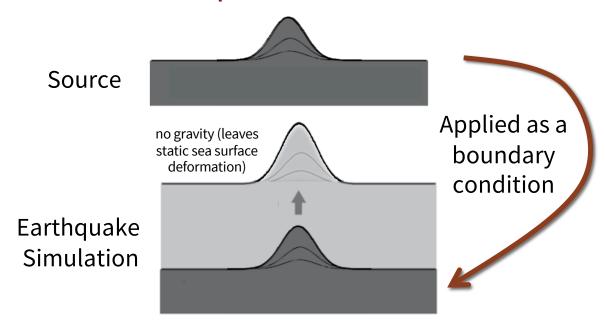
Acoustic waves significant? No if:

$$\frac{c\sigma_t}{H} \gg 1$$

Where, the ocean depth is $H=4\mathrm{km}$, tsunami wave speed is \sqrt{gH} , and acoustic wavespeed c









Problem setup Source no gravity (leaves static sea surface deformation) Earthquake Simulation one-way information flow Tsunami Simulation (modified from Saito et al., 2019)



Problem setup Source no gravity (leaves static sea surface deformation) Earthquake Simulation Static Initial condition one-way information flow Tsunami Simulation (modified from Saito et al., 2019)

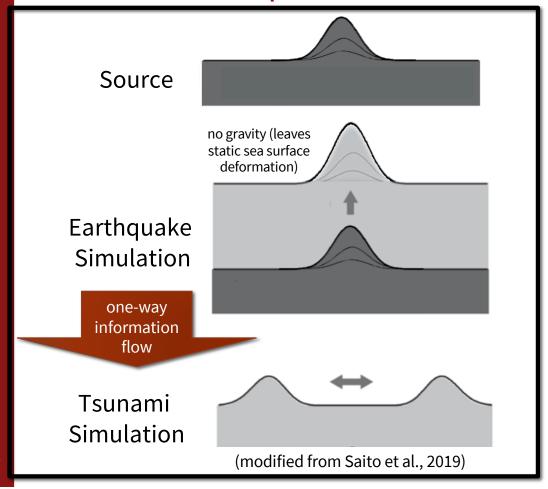


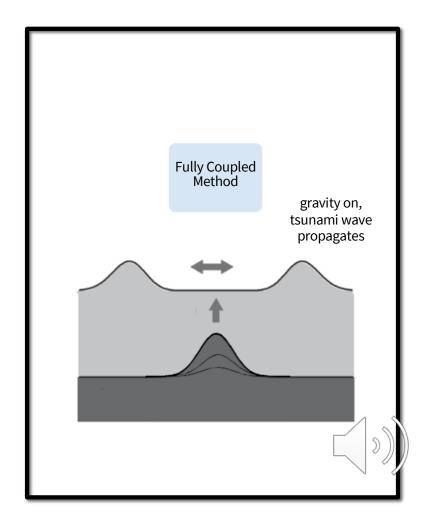
Problem setup Source no gravity (leaves static sea surface deformation) Time-dependent Seafloor Velocity Earthquake as Forcing Simulation Static Initial condition one-way information flow Tsunami Simulation (modified from Saito et al., 2019)



Problem setup Source Time-dependent Sea Surface Velocity as no gravity (leaves Forcing static sea surface deformation) Time-dependent Seafloor Velocity Earthquake as Forcing Simulation Static Initial condition one-way information flow Tsunami Simulation (modified from Saito et al., 2019)







Revised Slides Begin here

Research is always ongoing, this talk has been revised to show new exciting results!





Method 1.
Static Initial condition

Method 2. Time-dependent Seafloor Velocity as Forcing Method 3. Time-dependent Sea Surface Velocity as Forcing

Method 4. Fully Coupled Method

Example 1:

Source Width : $\sigma_r = 12.5 \text{ km}$

Source Duration : $\sigma_t = 500 \text{ s}$

Within shallow water limit?

Yes:
$$\frac{H}{\sigma_r} = 0.32 < 1$$

Tsunami propagates over source duration?

Yes:
$$\frac{\sigma_r}{\sigma_t \sqrt{gH}} = 0.13 < 1$$

Acoustic waves significant?

No:
$$\frac{c\sigma_t}{H} = 187.5 > 1$$

We can anticipate method 1 (using a static initial condition) will be incorrect

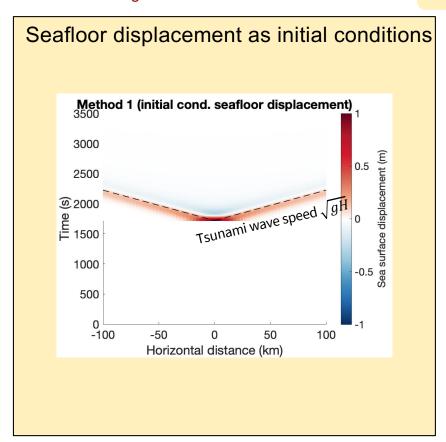


Yes: Tsunami propagates over source duration? No: Acoustic waves significant?

Method 1. Static Initial condition

Method 2. Time-dependent Seafloor Velocity as Forcing

Method 3. Time-dependent Sea Surface Velocity as Forcing

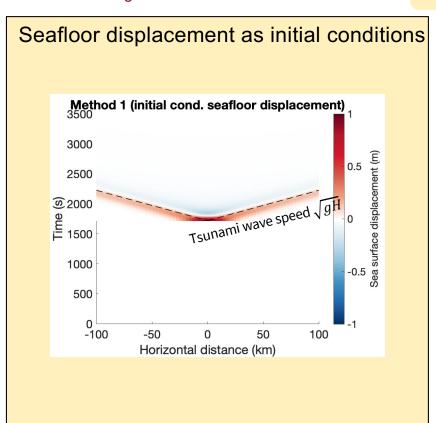


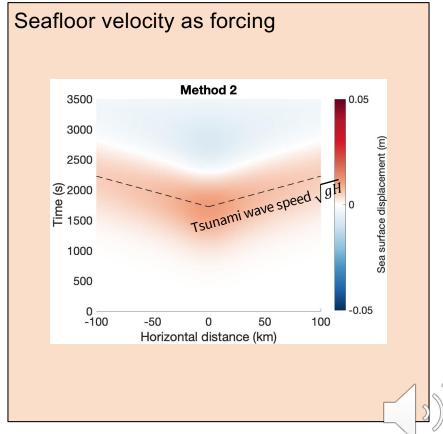


Yes: Tsunami propagates over source duration?

No: Acoustic waves significant?

Method 1. Static Initial condition Method 2. Time-dependent Seafloor Velocity as Forcing Method 3.
Time-dependent
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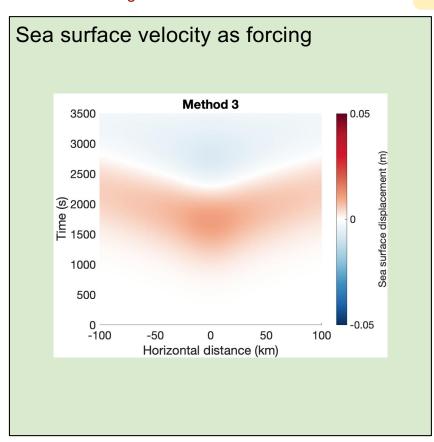


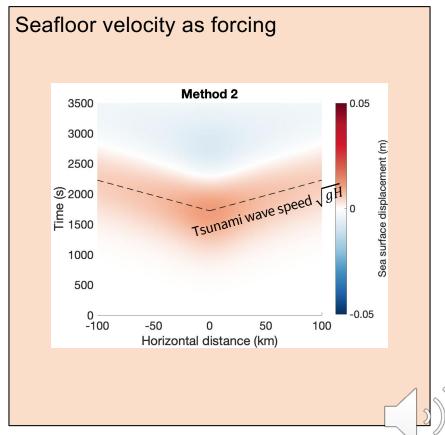


Yes: Tsunami propagates over source duration?

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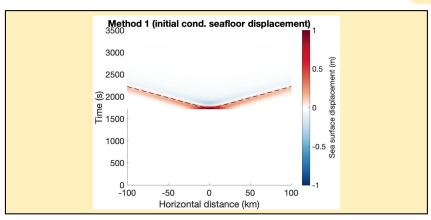


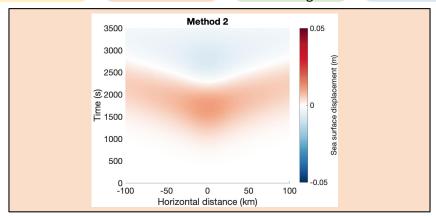
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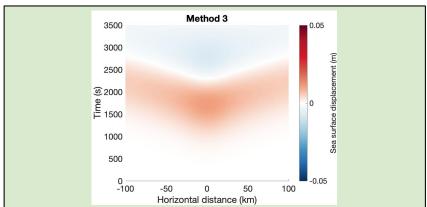
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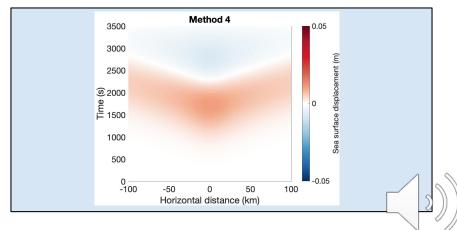
Method 2. Time-dependent Seafloor Velocity as Forcing

Method 3. Time-dependent Sea Surface Velocity as Forcing









Method 1.
Static Initial condition

Method 2. Time-dependent Seafloor Velocity as Forcing Method 3. Time-dependent Sea Surface Velocity as Forcing

Method 4. Fully Coupled Method

Example 2:

Source Width : $\sigma_r = 12.5 \text{ km}$

Source Duration : $\sigma_t = 1.25 \text{ s}$

Within shallow water limit?

Yes:
$$\frac{H}{\sigma_r} = 0.32 < 1$$

Tsunami propagates over source duration?

No:
$$\frac{\sigma_r}{\sigma_t \sqrt{gH}} = 50.5 > 1$$

Acoustic waves significant?

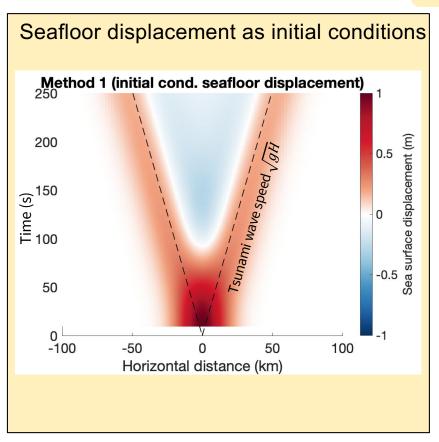
Yes:
$$\frac{c\sigma_t}{H} = 0.47 < 1$$

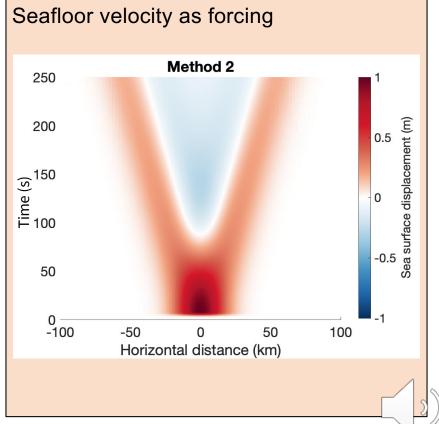
Method 1 and 2 do not model acoustic wave generation, we anticipate the results will differ compared to methods 3 and 4

No: Tsunami propagates over source duration?

Yes: Acoustic waves significant?

Method 1. Static Initial condition Method 2. Time-dependent Seafloor Velocity as Forcing Method 3.
Time-dependent
Sea Surface
Velocity as
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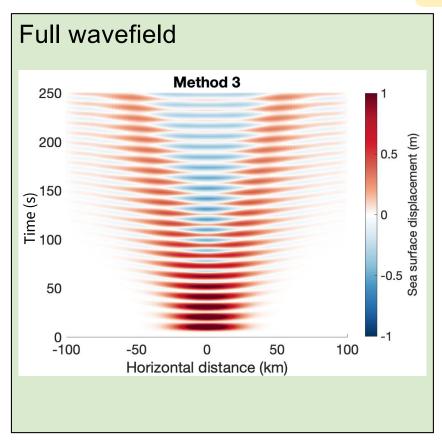


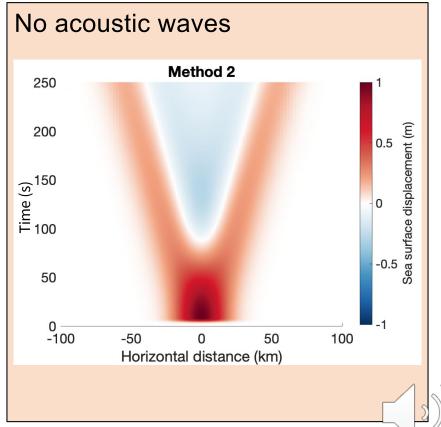
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Method 1. Static Initial condition

Method 2. Time-dependent Seafloor Velocity as Forcing

Method 3. Time-dependent Sea Surface Velocity as Forcing



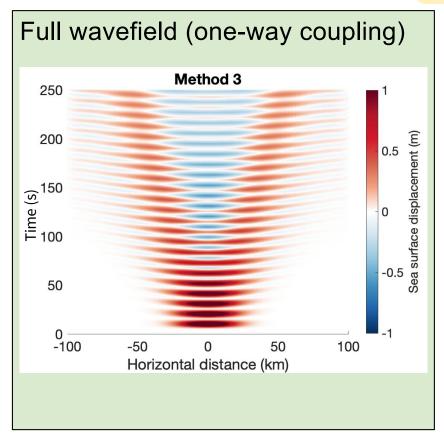


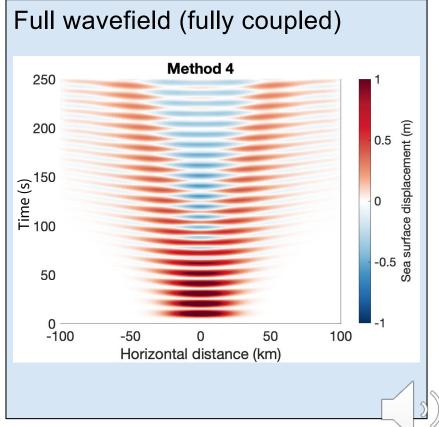
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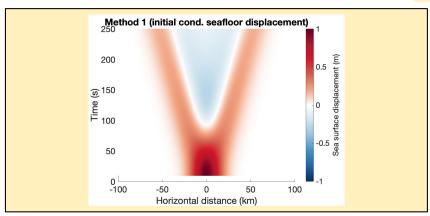


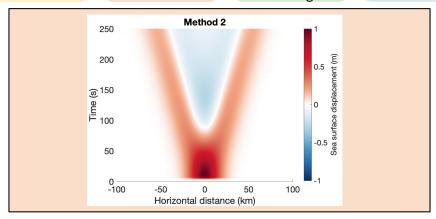
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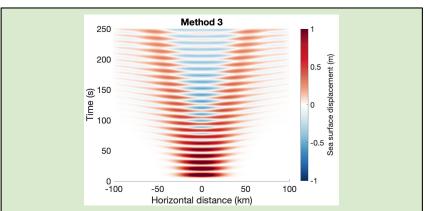
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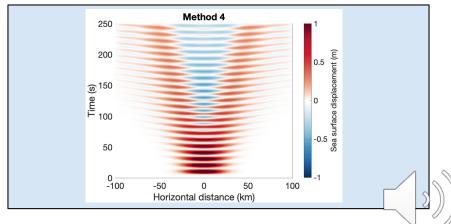
Method 2. Time-dependent Seafloor Velocity as Forcing

Method 3. Time-dependent Sea Surface Velocity as Forcing







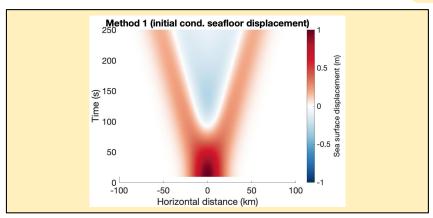


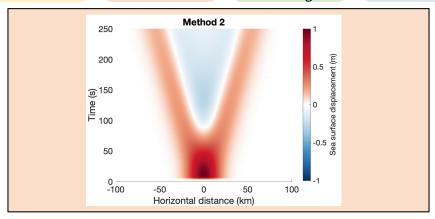
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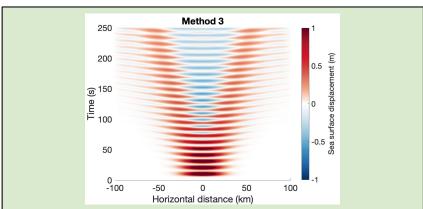
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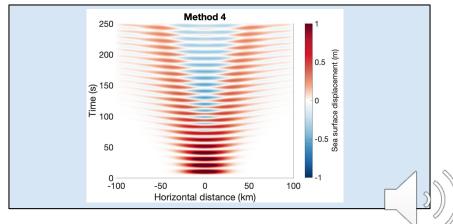
Method 2. Time-dependent Seafloor Velocity as Forcing

Method 3. Time-dependent Sea Surface Velocity as Forcing









Method 1.
Static Initial condition

Method 2. Time-dependent Seafloor Velocity as Forcing Method 3. Time-dependent Sea Surface Velocity as Forcing

Method 4. Fully Coupled Method

Example 3:

Source Width : $\sigma_r = 1.25 \text{ km}$

Source Duration : $\sigma_t = 1.25 \text{ s}$

Within shallow water limit?

No:
$$\frac{H}{\sigma_r} = 3.20 > 1$$

Tsunami propagates over source duration?

No:
$$\frac{\sigma_r}{\sigma_t \sqrt{gH}} = 5.05 > 1$$

Acoustic waves significant?

Yes:
$$\frac{c\sigma_t}{H} = 0.47 < 1$$

Method 1 and 2 do not model acoustic wave generation, we anticipate the results will differ compared to methods 3 and 4

*Note, in this study
Method 1, 2, and 3 all use a
linear shallow water solver not
accounting for dispersion
affects

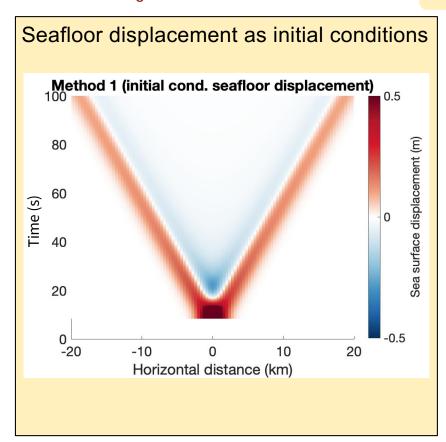


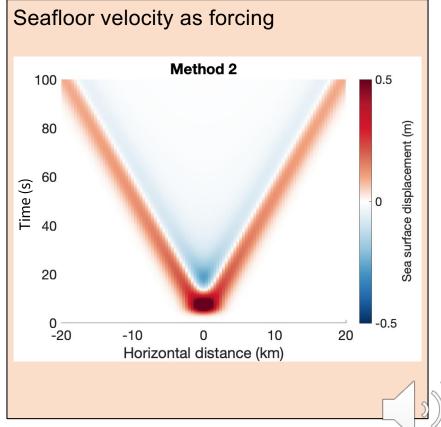
No: Tsunami propagates over source duration? Yes: Acoustic waves significant?

Method 1. Static Initial condition

Method 2. Time-dependent Seafloor Velocity as Forcing

Method 3. Time-dependent Sea Surface Velocity as Forcing

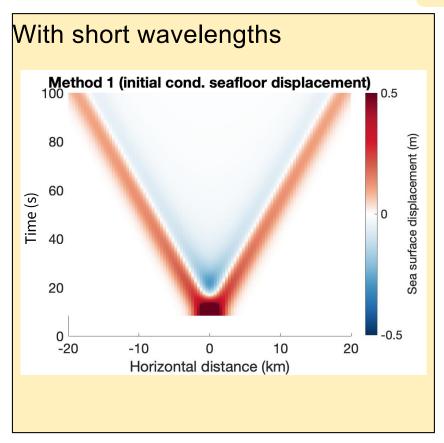


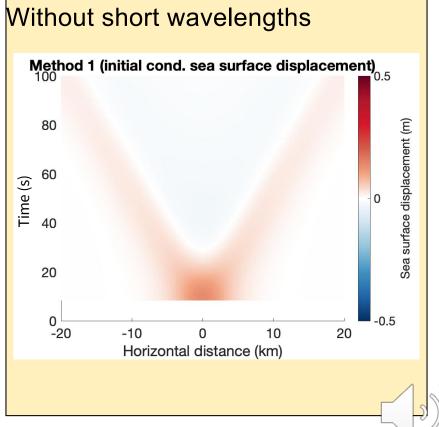


No: Tsunami propagates over source duration?

Yes: Acoustic waves significant?

Method 1. Static Initial condition Method 2. Time-dependent Seafloor Velocity as Forcing Method 3.
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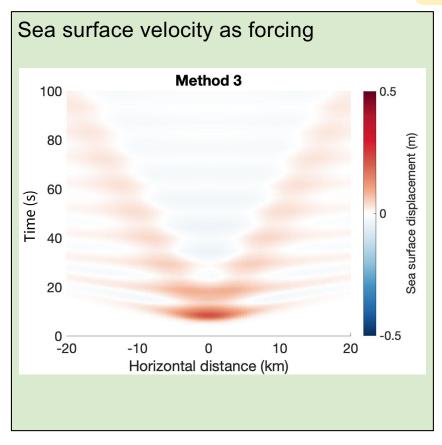


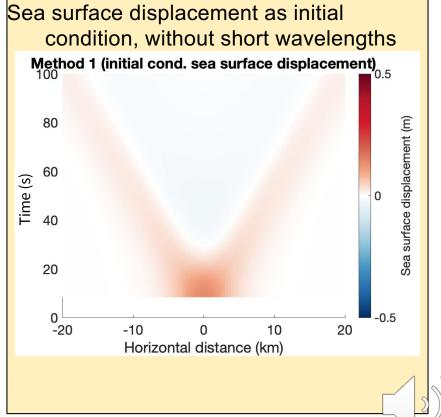


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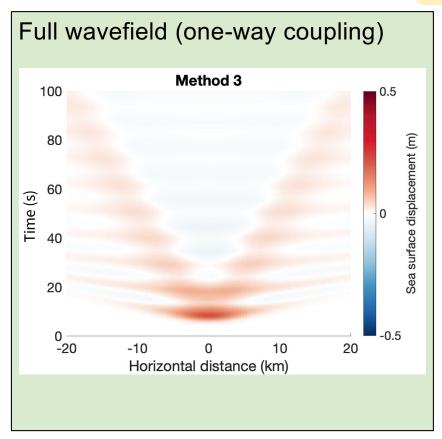


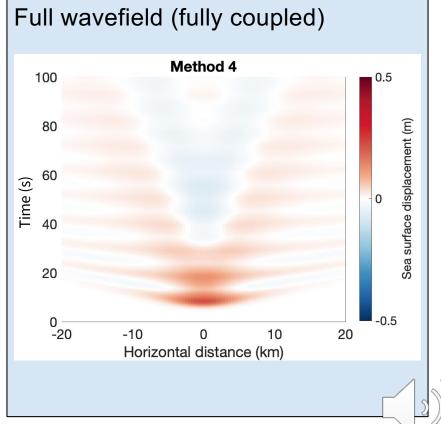


No: Tsunami propagates over source duration?

No: Acoustic waves significant?

Method 1. Static Initial condition Method 2. Time-dependent Seafloor Velocity as Forcing Method 3.
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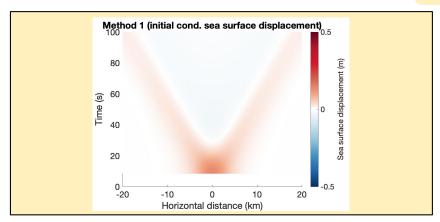


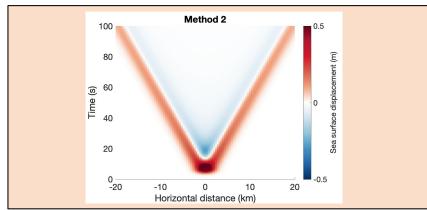
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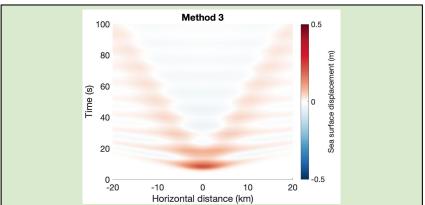
Method 1. Static Initial condition

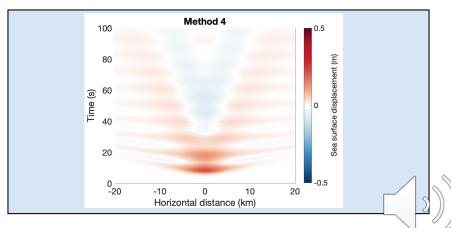
Method 2. Time-dependent Seafloor Velocity as Forcing

Method 3. Time-dependent Sea Surface Velocity as Forcing









Static Initial Conditions

Final earthquake seafloor or sea surface uplift recorded

Set initial tsunami sea surface height

Requires:

Shallow water limit (if short wavelength are not filtered)

$$\frac{H}{\sigma_r} \ll 1$$

Tsunami waves do not propagate over source duration

$$\frac{\sigma_r}{\sigma_t \sqrt{gH}} \gg 1$$

And acoustic waves are not generated

$$\frac{c\sigma_t}{H} \gg 1$$

Time-dependent Seafloor Velocity as Forcing

Record earthquake seafloor velocity

Set time-dependent forcing in the tsunami mass balance

Requires:

Shallow water limit

$$\frac{H}{\sigma_r} \ll 1$$

And acoustic waves are not generated

$$\frac{c\sigma_t}{H} \gg 1$$

Time-dependent Sea Surface Velocity as Forcing

Solves earth and ocean response without gravity

Use sea surface velocity as a forcing term in a tsunami simulation

If non-dispersive shallow water solver, requires: Shallow water limit

$$\frac{H}{\sigma_r} \ll 1$$

If Boussinesq tsunami solver: We expect valid in more cases

Fully Coupled Method (SeisSol)

Simultaneously solves earthquake rupture, seismic waves, and ocean response (including gravity)

http://www.seissol.org/

Valid in all cases



Static Initial Conditions

Final earthquake seafloor or sea surface uplift recorded

Set initial tsunami sea surface height

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Shallow water limit (if short wavelength are not filtered)

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And acoustic waves are not generated

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Time-dependent Seafloor Velocity as Forcing

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Requires:

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And acoustic waves are not generated

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Time-dependent Sea Surface Velocity as Forcing

Solves earth and ocean response without gravity

Use sea surface velocity as a forcing term in a tsunami simulation

If non-dispersive shallow water solver, requires: Shallow water limit

$$\frac{H}{\sigma_r} \ll 1$$

If Boussinesq tsunami solver: We expect valid in more cases

Fully Coupled Method (SeisSol)

Simultaneously solves earthquake rupture, seismic waves, and ocean response (including gravity)

http://www.seissol.org/

Valid in all cases



Static Initial Conditions

Final earthquake seafloor or sea surface uplift recorded

Set initial tsunami sea surface height

Requires:

Shallow water limit (if short wavelength are not filtered)

$$\frac{H}{\sigma_r} \ll 1$$

Tsunami waves do not propagate over source duration

$$\frac{\sigma_r}{\sigma_t \sqrt{gH}} \gg 1$$

And acoustic waves are not generated

$$\frac{c\sigma_t}{H} \gg 1$$

Time-dependent Seafloor Velocity as Forcing

Record earthquake seafloor velocity

Set time-dependent forcing in the tsunami mass balance

Requires:

Shallow water limit

$$\frac{H}{\sigma_r} \ll 1$$

And acoustic waves are not generated

$$\frac{c\sigma_t}{H} \gg 1$$

Time-dependent Sea Surface Velocity as Forcing

Solves earth and ocean response without gravity

Use sea surface velocity as a forcing term in a tsunami simulation

If non-dispersive shallow water solver, requires: Shallow water limit

$$\frac{H}{\sigma_r} \ll 1$$

If Boussinesq tsunami solver: We expect valid in more cases

Fully Coupled Method (SeisSol)

Simultaneously solves earthquake rupture, seismic waves, and ocean response (including gravity)

http://www.seissol.org/

Valid in all cases



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